

# Feasibility of using UAV-based LiDAR to estimate biomass in Icelandic forests:

## A test case from Fljótsdalur, east Iceland

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S V A R M I

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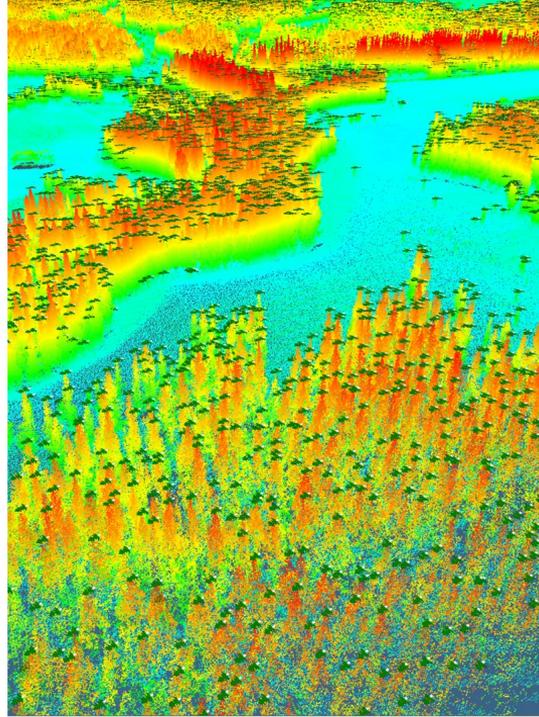
Skógrækt 2030– *Ábyrg græn Framtíð*, 29 - 30 March 2022, Haukadalur, Iceland

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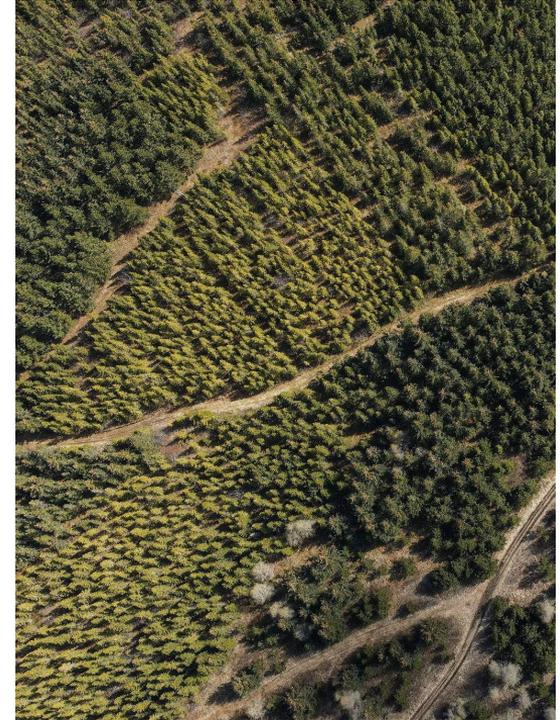
# Yfirlit kynningar



Part 1:  
What is Svarmi?



Part 2:  
UAV LiDAR Fjótisdalur  
Method & Results



Part 3:  
Future of UAV LiDAR in  
Icelandic forestry





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# Svarmi

- **Landlíkön og loftmyndir** þar sem stuðst er við gervitungl og dróna
- **Útdráttur upplýsinga** úr þessum gögnum meðal annars með vélrænum lærdómi
- **DATACT®** hugbúnaður sem eykur yfirsýn og auðveldar aðgengi að háupplausna gögnum í tíma og rúmi
- **Stuðlar að sjálfbærni** með bættri vöktun á umhverfi og innviðum

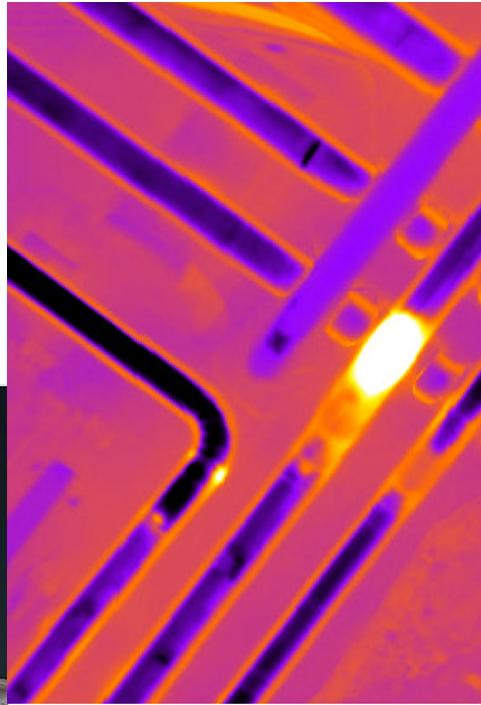




LiDAR  
Scanning



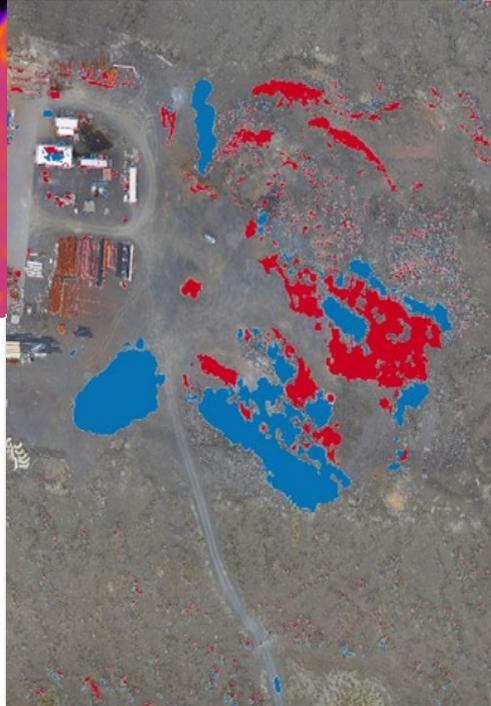
Highest-resolution  
Aerial Imagery  
& 3d Models



Thermal &  
Multispectral  
Imagery



Image  
Analysis





# UAV LiDAR Flights

- Forested area in Fljótsdalur, East Iceland
- 3 Flights in total
- Total of about half a day of fieldwork
- Mapped about 150 ha in high resolution
- Forest is mainly Siberian Larch (rússalerki)



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# LiDAR Pointcloud Of the forest

- Took a few hours to produce a pointcloud of the area
- Accuracy +/- 3 cm
- 100 - 150 pt/m<sup>2</sup> point density
  - Enough to see individual trees, but not to measure DBH

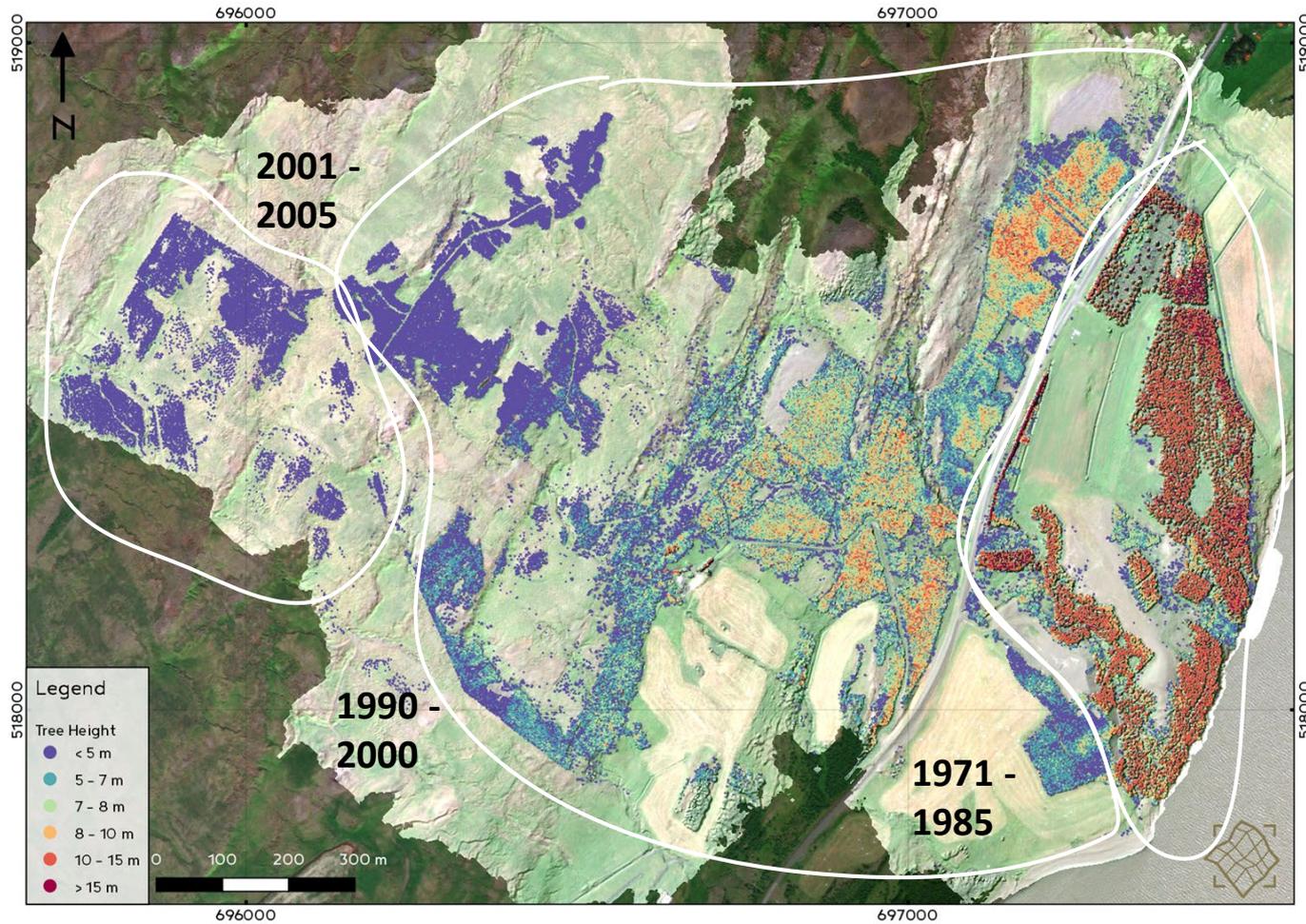


# Data Segmentation & Classification

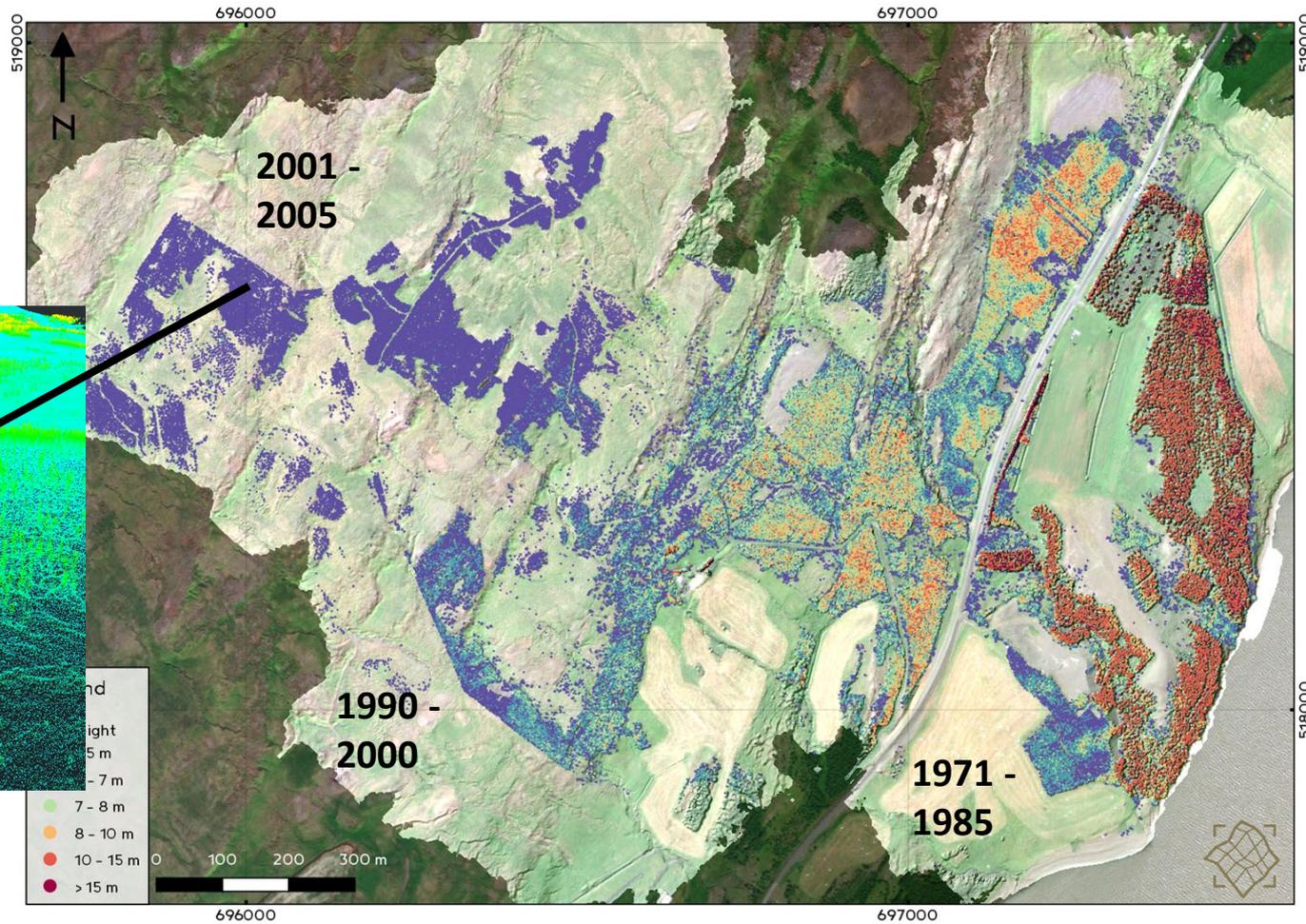
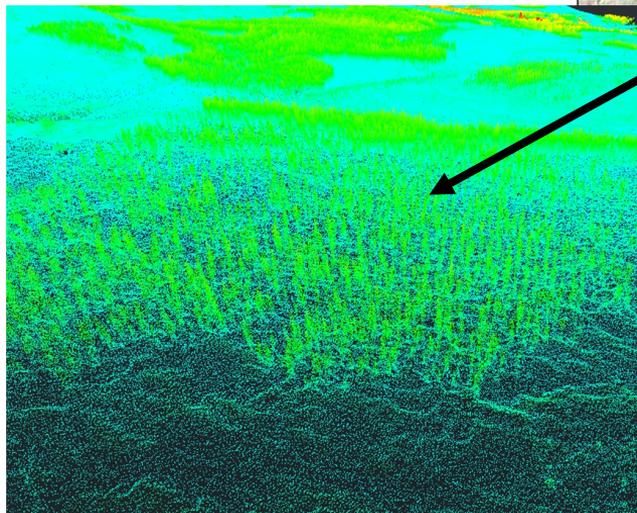
- DTM (ground terrain model below trees) also created
- Tree canopy height model created, isolating tree points from ground

## Strata Segmentation:

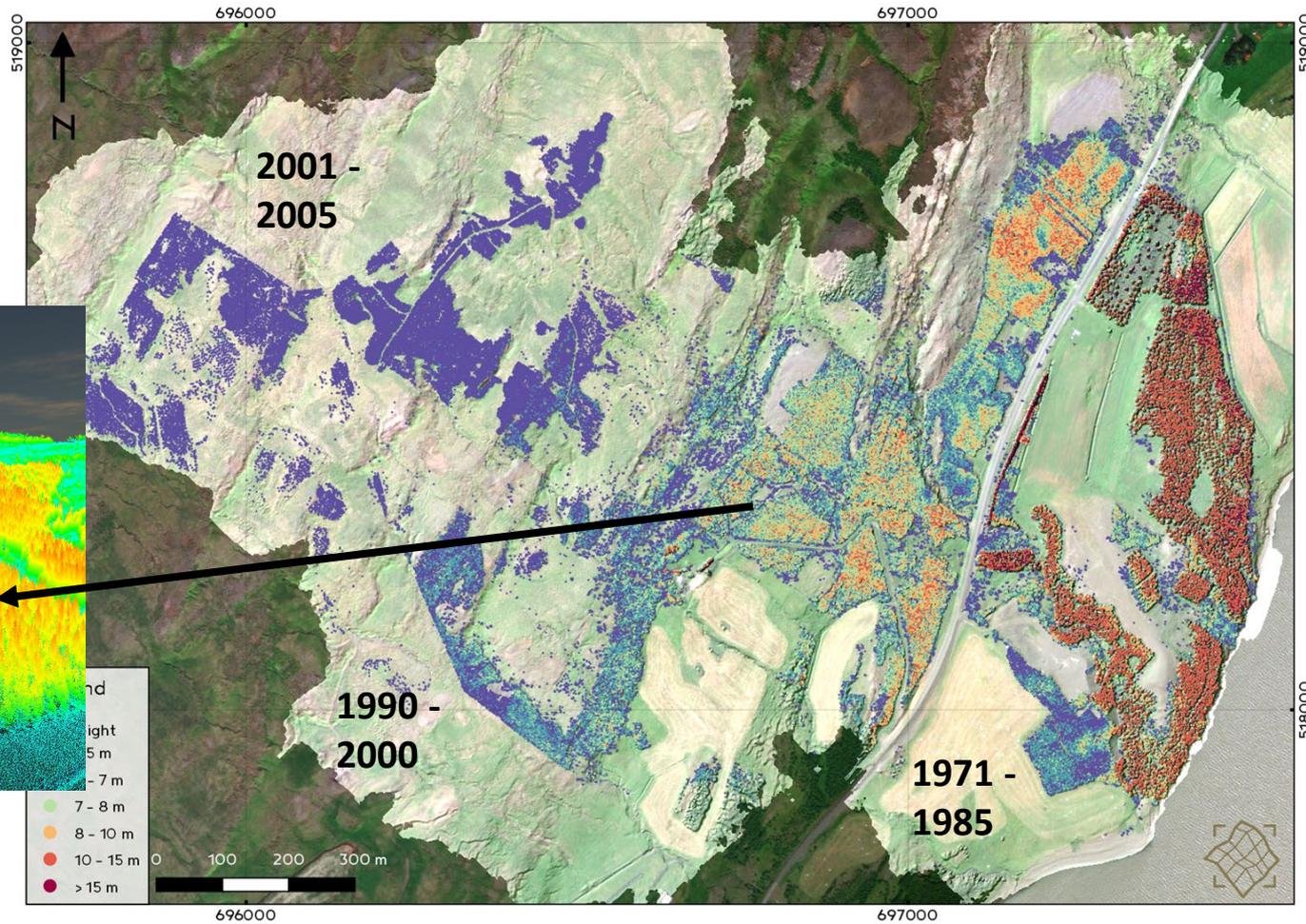
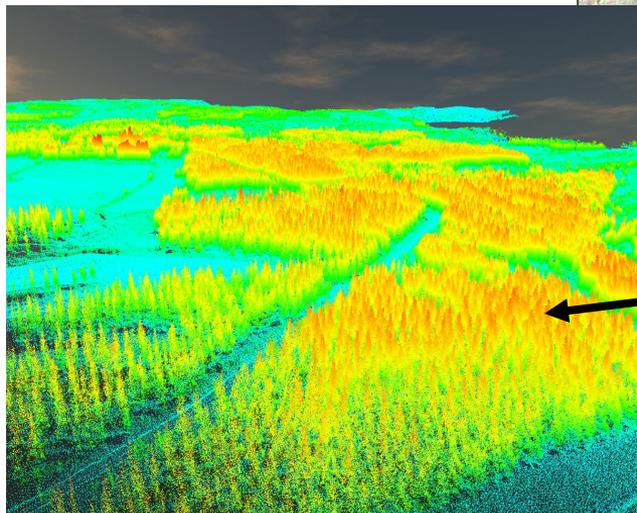
- Divided into 3 categories (strata) by age
- Growth rates and filters were applied differently to each strata area



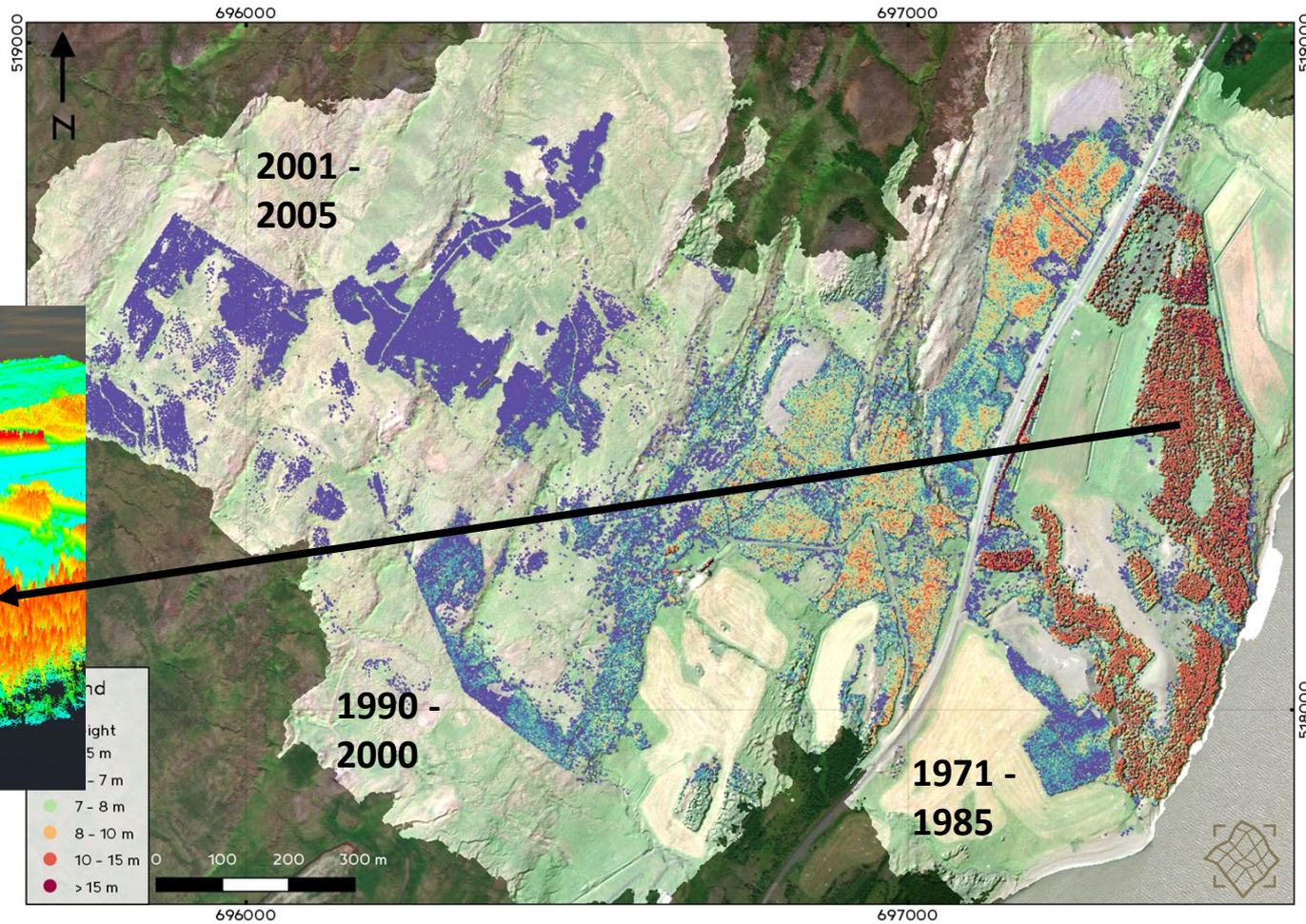
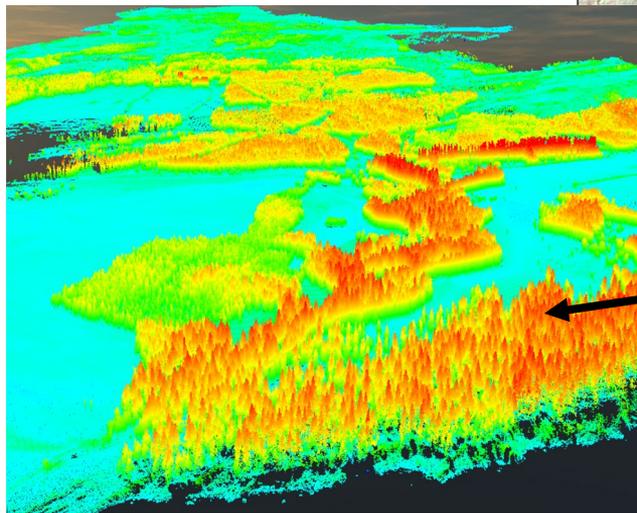
# Data Segmentation & Classification



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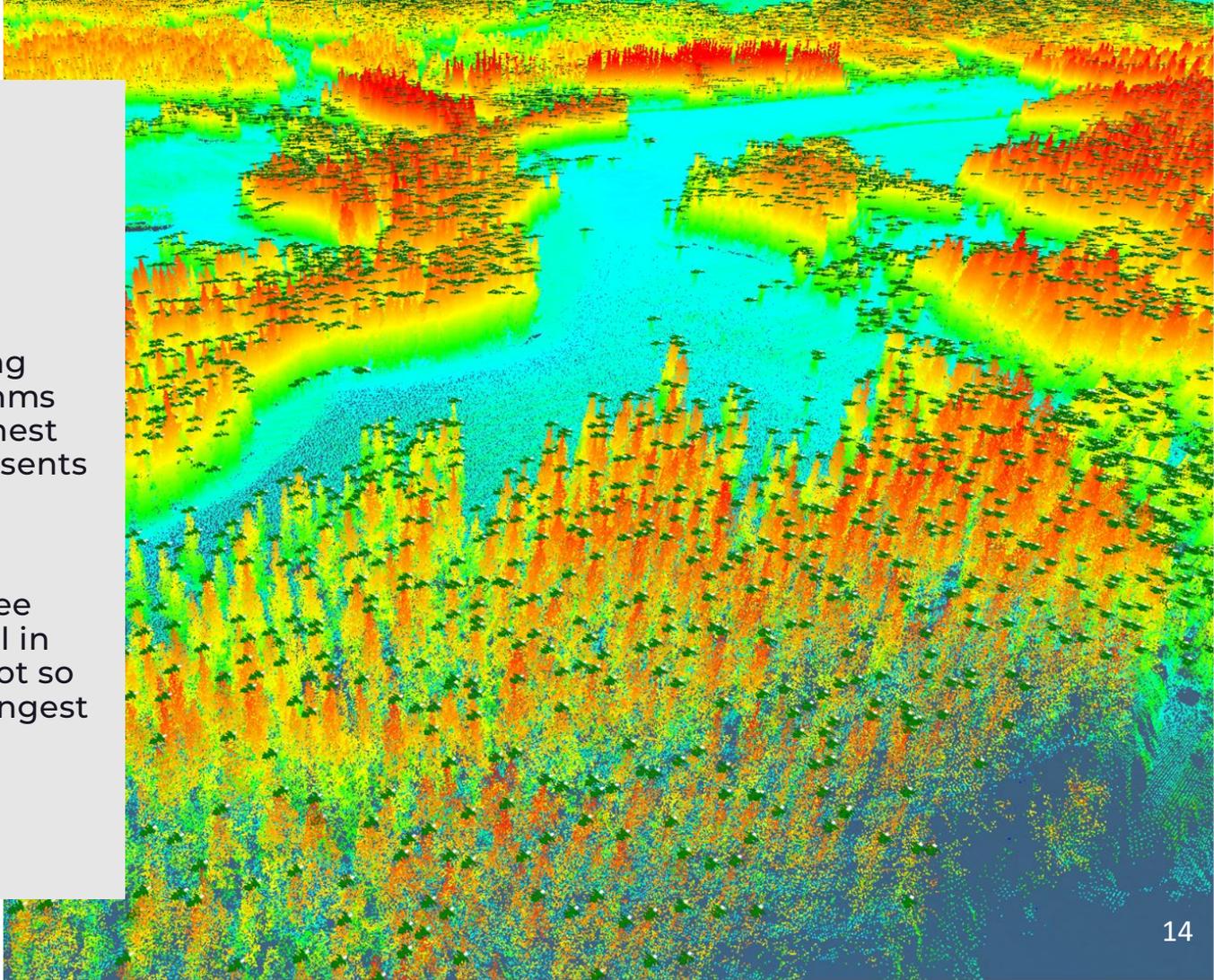
# Data Segmentation & Classification



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# Processing LiDAR data

- Trees were identified using machine learning algorithms developed at Svirmi, highest point in tree cluster represents tree height
- Visual analysis showed tree identification worked well in areas where trees were not so dense (i.e. oldest and youngest strata)

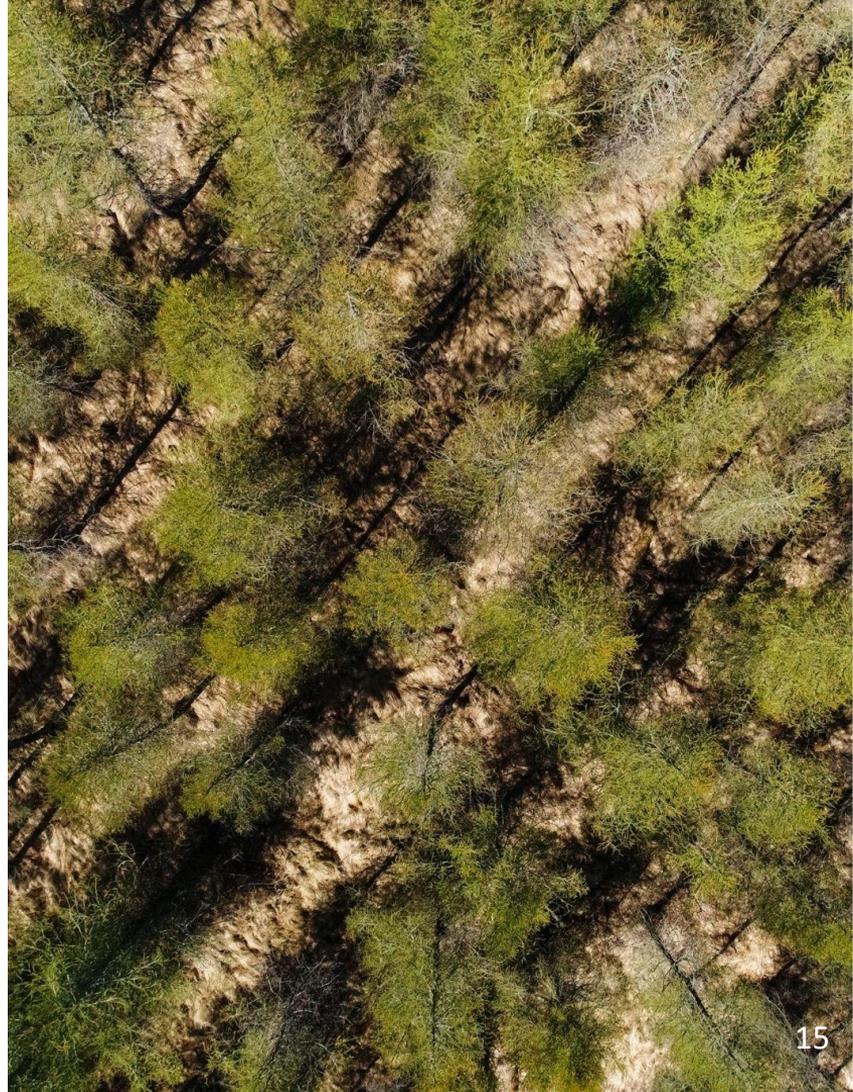


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# Linear Regression Model

Predicting DBH/Biomass from tree height

- Used field data from rússalerki in east Iceland to create a regression model relating tree height to DBH
- Applicable in this case on mostly single-species forest in the same area, altitude, etc.
- Each tree assigned a biomass based on height calculated from regression



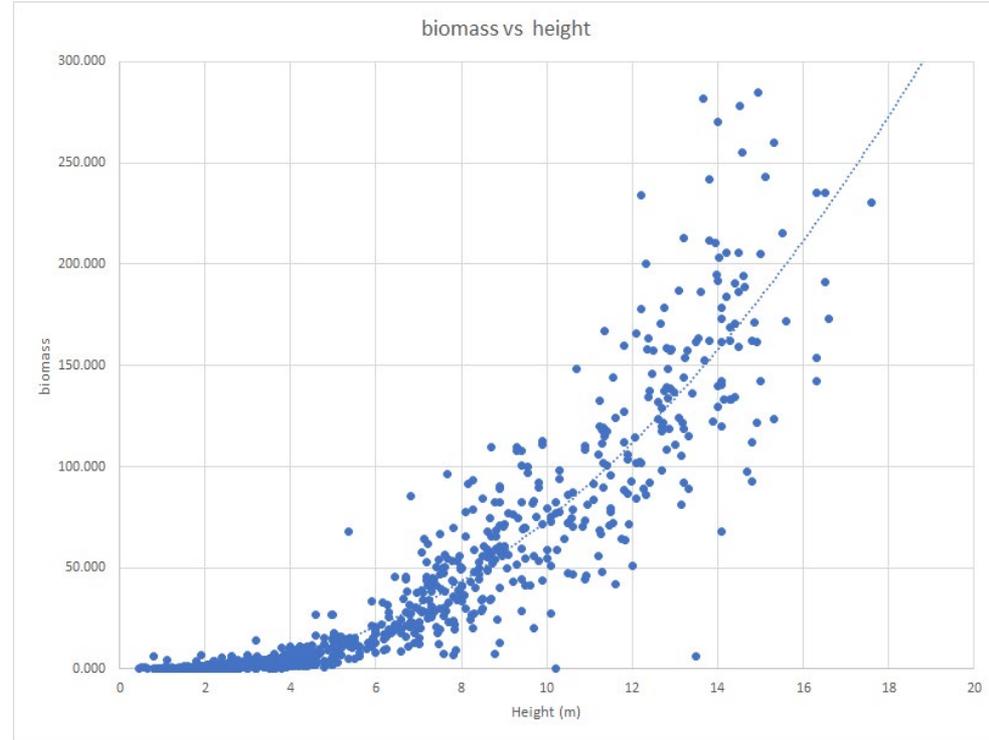
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# Linear Regression Model

Predicting Biomass from tree height

- Each tree assigned a biomass based on height calculated from regression

$$\text{Biomass (kg carbon)} = 0.0978 * (\text{height}^{2.7854})$$

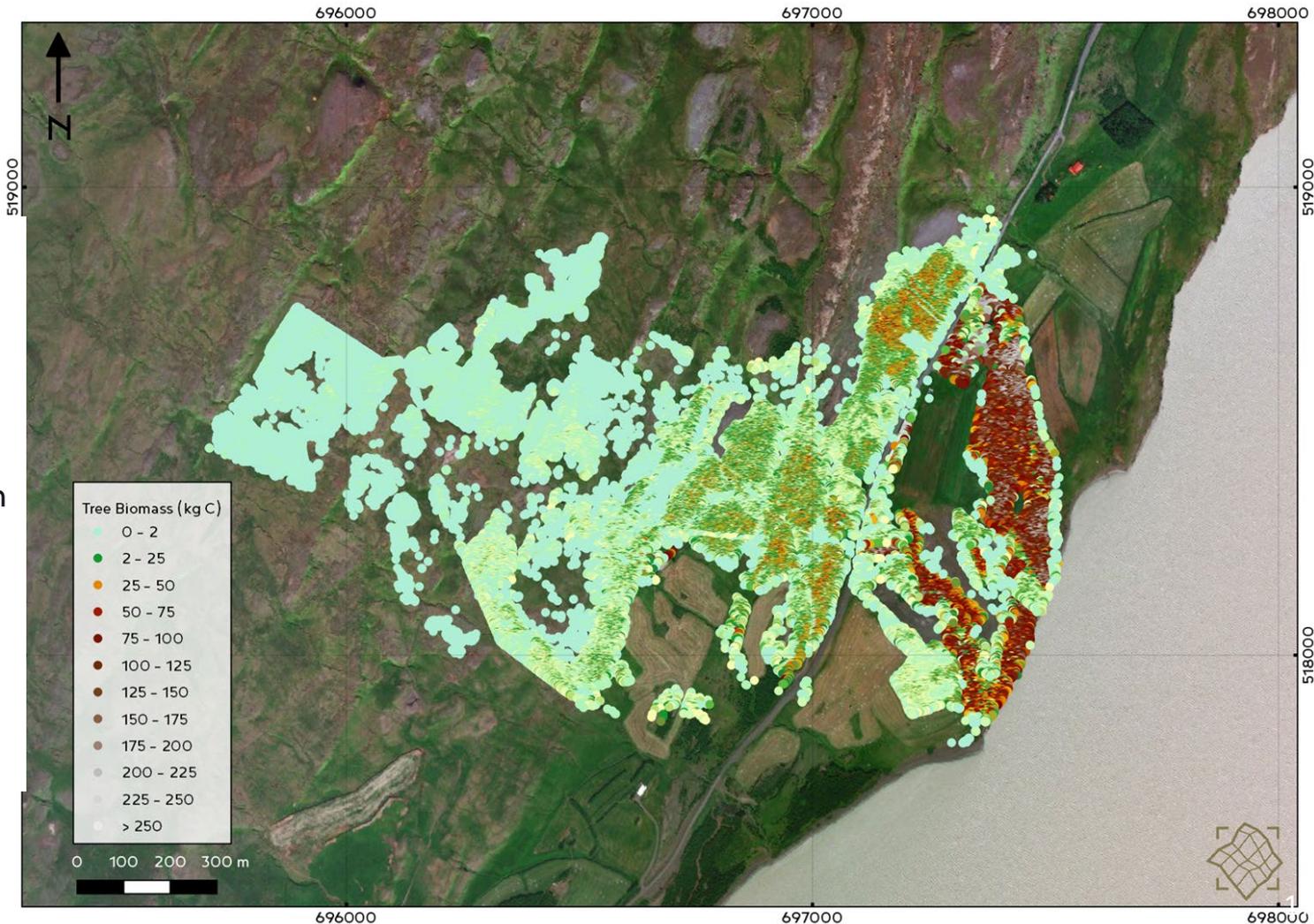


$R^2 = 0.89$



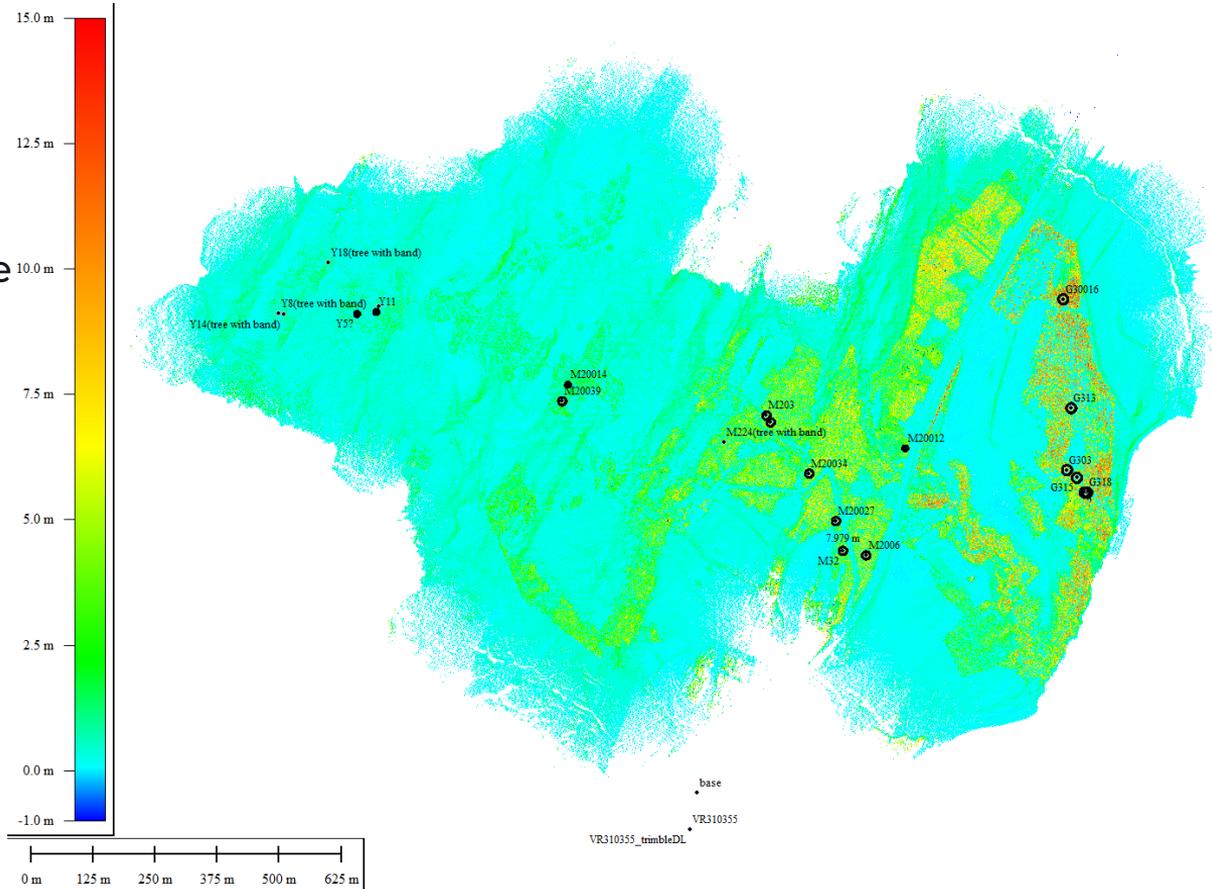
# Estimated Biomass

- Each point represents an individual tree
- Biomass estimate can be given for the whole forest in matter of minutes with regression analysis



# Accuracy

- 26 plots measured in situ were compared with the same areas on the pc to estimate accuracy
- Individual trees were compared side-by-side when possible
- Biomass for the entire plot was also estimated

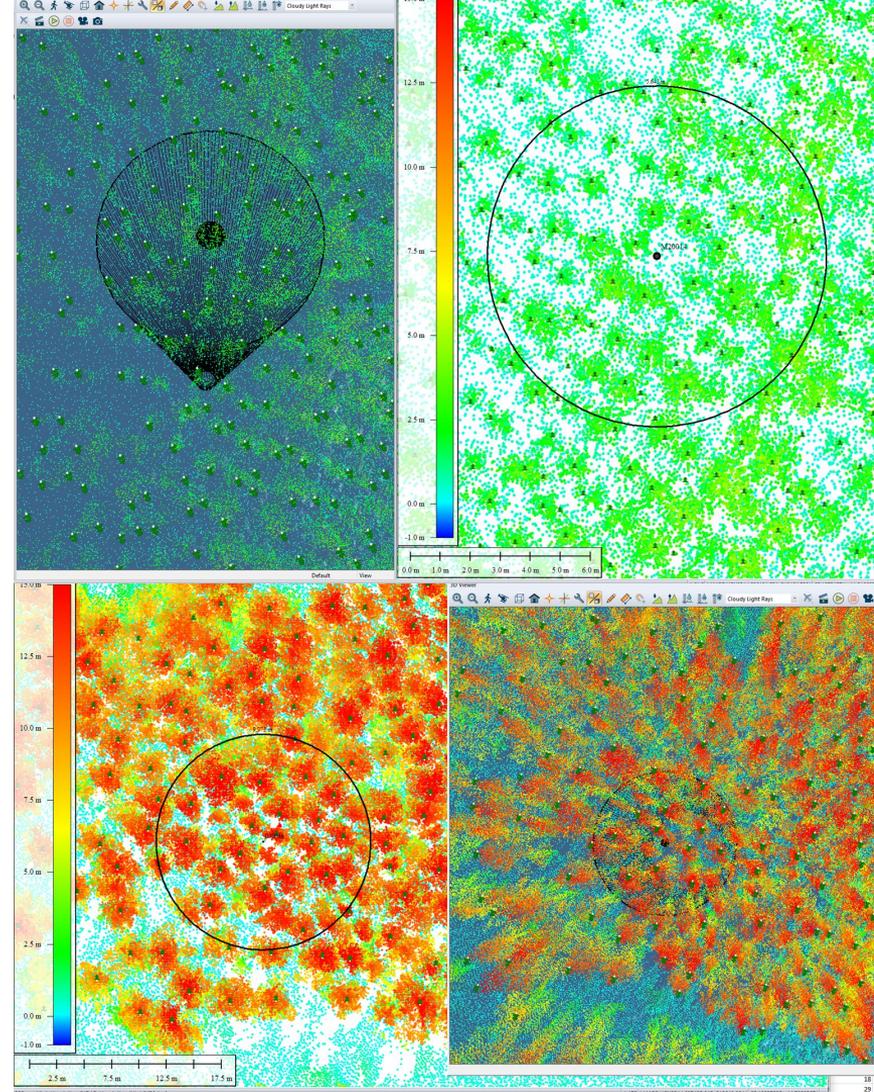


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# Accuracy

## Biomass Plot Comparison

- Trees measured in the field were compared for accuracy in each strata
- It was not always possible to compare individual trees, so the biomass of the entire plot was estimated instead



# Accuracy

## In-situ Biomass compared to LiDAR method

- Overall error for all strata within 6%
- Slight overestimate in middle strata, where trees are densely planted
  - Treetops could not be easily identified from branches; too many treetops
- Slight underestimate of biomass in oldest strata
  - Smaller trees in between were likely filtered out by mistake; slight breakdown of the regression model accuracy here as well (high scatter in data)
- Smallest error in youngest strata (under 3%)
  - Individual trees easily identifiable; regression seemed to work well here

Plot	Biomass Measured	Biomass LiDAR est.	Difference	Error (%)	Measurement
10005	85.05	79.80	-5.25	-6.18	GPS
10008	41.70	31.30	-10.40	-24.93	GPS
10011	39.19	27.90	-11.30	-28.82	GPS
10013	44.43	32.08	-12.35	-27.80	Shifted
10014	55.44	49.12	-6.32	-11.40	GPS
10018	35.55	58.16	22.61	63.59	GPS
10025	160.65	159.32	-1.33	-0.83	Shifted
10050	48.84	56.28	7.44	15.24	Shifted
20006	1316.37	1773.47	457.10	34.72	GPS
20012	743.05	1034.19	291.14	39.18	GPS
20014	161.92	251.35	89.43	55.23	GPS
20023	682.88	923.13	240.25	35.18	Shifted
20027	1670.64	1908.21	237.57	14.22	GPS
20032	719.41	694.38	-25.03	-3.48	GPS
20034	1607.68	2028.15	420.47	26.15	GPS
20039	546.30	658.21	111.91	20.48	GPS
20203	1193.67	1125.26	-68.41	-5.73	GPS
20222	1339.77	1574.73	234.95	17.54	GPS
20224	1388.58	1541.69	153.11	11.03	GPS
20238	1013.99	1211.56	197.56	19.48	Shifted
20240	1231.40	1171.51	-59.88	-4.86	Shifted
30016	5146.43	4058.52	-1087.91	-21.14	GPS
30303	2837.24	1880.45	-956.79	-33.72	GPS
30313	1720.26	1789.18	68.91	4.01	GPS
30315	1267.37	810.12	-457.25	-36.08	GPS
30318	2414.39	2262.18	-152.20	-6.30	GPS

<b>Overall Error</b>	<b>-12.38</b>	<b>5.57 % overestimate</b>
<b>Youngest</b>	<b>-2.11</b>	<b>-2.64 % underestimate</b>
<b>Middle</b>	<b>175.40</b>	<b>19.93 % overestimate</b>
<b>Oldest</b>	<b>-517.05</b>	<b>-18.65 % underestimate</b>



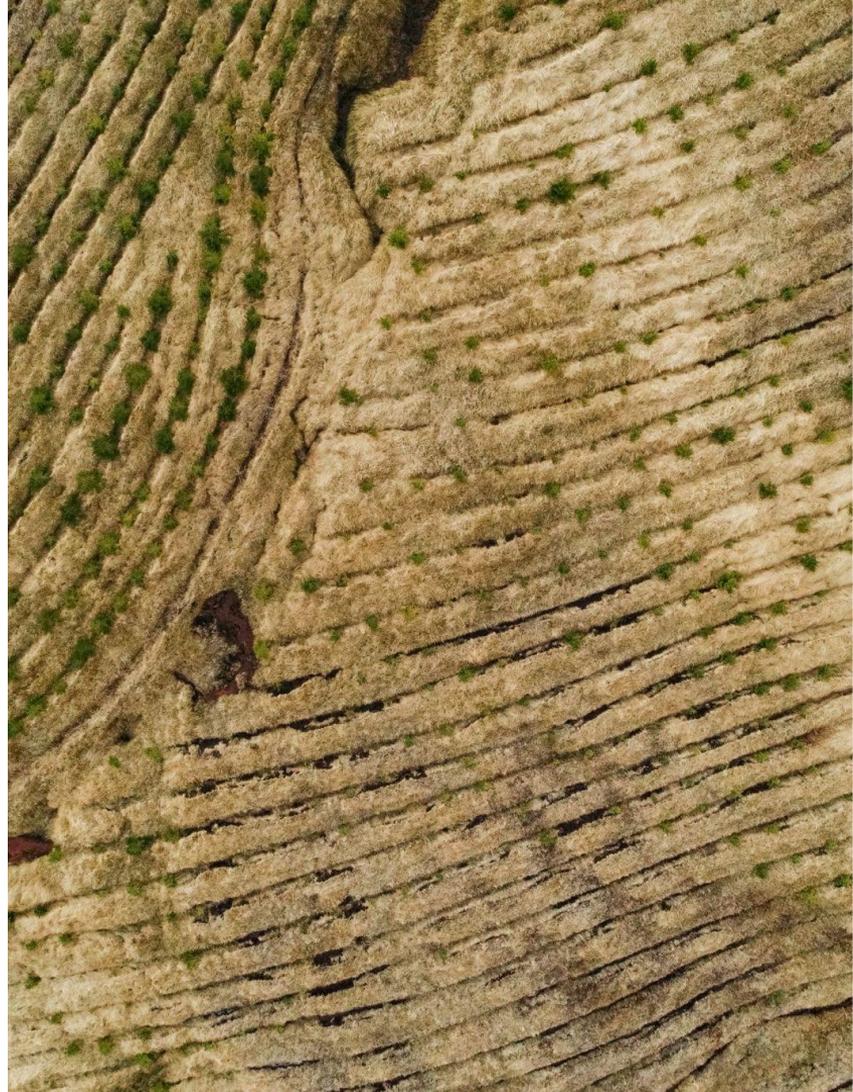


# Future of LiDAR Remote Sensing in Forestry Applications

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# Improvements to LiDAR forest measurement

- Good GPS measurements on field plots important for error estimate
- More imagery types (RGB, MSI) can help to segment out individual trees in densely planted areas as well as help in classifying multiple species
- Regression model could be improved with more field data



# Benefits of LiDAR / Remote sensing data in forestry

- Quick & relatively cheap georeferenced 'snapshot' of the forest
  - can be processed later & compared to later datasets
- Inventory of entire forest taken at once
- Measurements are very accurate ( $\pm 3$  cm)
- DTM (terrain model below trees) can be given as well as ortho
- Tree growth could be measured for entire forest year-to-year
- Forest boundary extent can be easily updated....





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Takk!

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